CHAPTER 9 PROBLEMS OUTLINE OF SOLUTIONS

1. We use the relationship $s = r \theta$; s is arc length, r is radius, θ is angle subtended.

$$\theta = \frac{s}{r} = \frac{0.75 \text{ m}}{2.5 \text{ m}} = 0.3 \text{ radians} = 17.2 \text{ degrees.}$$

3. The second hand completes 2π radians in 60 s, so $\omega = 2 \pi$ rad/60 s = 0.10 rad/s. The minute hand completes 2π radians in 3600 seconds, so $\omega = 2 \pi$ rad/3600 s = 0.0017 rad/s. The hour hand completes 2π radians in 12 hours (assuming a 12 hour clock as is typical in the United States); so its angular velocity is 1/12 that of the minute hand.

5. $\omega = 2\pi/2.25$ s = 2.779 rad/s. The period is stated; it is 2.25 s.

7. Distance to the moon is 384, 000 km. $v = r \omega$ so the linear velocity across the moon is :

$$v = 3.84 \times 10^8 \,\mathrm{m} \cdot 1.5 \,10^{-3} \,\mathrm{rad}/\mathrm{s} =$$

 5.76×10^5 m/s (make sure to convert distance to moon to meters).

We can find the half angle of divergence from :

$$\tan \theta = 3 \text{ km} / 384,000 \text{ km} = 7.81 \times 10^{-6}$$

Remember that for small angles, and this certainly qualifies, $\tan \theta \approx \theta$ (measured in radians), so the half angle is 7.81 10⁻⁶ rad, and the full angle is twice this.

s

9. a) 1900 rev/min = 1900 rev/min *
$$(2 \pi \operatorname{rad}/\operatorname{rev})(1 \min/60 \operatorname{s}) = 198.9 \operatorname{rad}/60^\circ$$

b) $\omega = \frac{\Delta \theta}{\Delta t} \Rightarrow \Delta t = \frac{\Delta \theta}{\omega} = \frac{35^\circ * 2 \pi \operatorname{rad}/360^\circ}{198.9 \operatorname{rad}/s} = 0.0031 \operatorname{s}$
c) 18 rad/s = 18 rad/s * 1 rev/ 2π rad * 60 s/min = 172 rev/min
d) The period is the time to make one revolution
so if the propeller has an angular velocity of 199 rad/s,
it will complete 1 rev $(2 \pi \operatorname{rad})$ in $2 \pi \operatorname{rad}/199 \operatorname{rad}/s = 0.032 \operatorname{s}$
11. $\alpha = \frac{\Delta \omega}{\Delta t} = \frac{78 \operatorname{rev}/\min * 2 \pi \operatorname{rad}/\operatorname{rev} * 1 \min/60 \operatorname{s}}{3.5 \operatorname{s}} = 2.33 \operatorname{rad}/\operatorname{s}^2$
 $\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2 = 0 + 0 + 0.5 * 2.33 \operatorname{rad}/\operatorname{s}^2 * (3.5 \operatorname{s})^2 = 14.3 \operatorname{rad} = 818^\circ$
13. 570 rpm = 570 rev/min $* 2 \pi \operatorname{rad}/\operatorname{rev} * 1 \min/60 \operatorname{s} = 60 \operatorname{rad/s}$
1600 rev/min = 167 rad/s
 $\alpha = \frac{\Delta \omega}{\Delta t} = (167 \operatorname{rad/s} - 60 \operatorname{rad/s})/(133 \min * 60 \operatorname{s}/\min) = 0.0135 \operatorname{rad/s}^2$
15. $\alpha = \frac{\Delta \omega}{\Delta t} \Rightarrow \Delta t = \frac{\Delta \omega}{\alpha} = (8 \operatorname{rad/s} - 0)/0.64 \operatorname{rad/s}^2 = 12.5 \operatorname{s}$

$$\theta = \theta_0 + \omega_0 + 0.5 \alpha t^2 = 0 + 0 + 0.5 * 0.64 \frac{\text{rad}}{\text{s}^2} * (12.5 \text{ s})^2 = 50 \text{ rad} = 7.96 \text{ revs}$$

(For the remainder of the problems, I will not write out explicitly conversion from rpm to rad/s)

17. We find the angular acceleration :

$$\theta = \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\theta = 200 \text{ rev} = 1256 \text{ rad}; \ \omega_0 = 500 \text{ rpm} = 52.3 \text{ rad/s}; \ t = 30 \text{ s}$$

$$1256 \text{ rad} = 52.3 \text{ rad/s} * 30 \text{ s} + 0.5 * \alpha (30 \text{ s})^2$$

$$-314 \text{ rad} = 0.5 * \alpha (900 \text{ s}^2) \Rightarrow \alpha = \frac{-314 \text{ rad}}{0.5 * 900 \text{ s}^2} = -0.7 \frac{\text{rad}}{\text{s}^2}$$

Knowing the angular acceleration, we know

$$\frac{\Delta\omega}{\Delta t} = \alpha \implies \omega_{\rm f} - \omega_{\rm o} = \alpha t$$

$$\omega_{\rm f} = \omega_{\rm o} + \alpha t = 52.3 \, \text{rad/s} - 0.7 \, \text{rad/s}^2 * 30 \, \text{s} = 31.3 \, \text{rad/s}$$

At this angular acceleration,

it would take $\Delta t = \Delta \omega / \alpha = -52.3 \text{ rad} / \text{s} / -0.7 \text{ rad} / \text{s}^2 = 74.7 \text{ s to stop}$

In this time, the flywheel will spin through the angle :

$$\theta = \omega_{o} t + 0.5 * \alpha t^{2} = 52.3 rad / s * 74.7 s - 0.5 * 0.7 rad / s^{2} * (74.7 s)^{2} = 1954 rad$$

19. We can use

$$\theta = \omega_0 t + 0.5 * \alpha t^2$$

$$\omega_0 = \frac{(\theta - 0.5 \alpha t^2)}{t} = \frac{60 \text{ rad} - 0.5 * 2.25 \text{ rad} / s^2 * 16 s^2}{4 \text{ s}} = 10.5 \text{ rad} / \text{ s}$$

21. Ugh unit conversions. We will use
$$v = r \omega$$
, but first :
 $v = 63 \text{ mi/h} = 63 \text{ mi/h} (5280 \text{ ft/mi} * 1 \text{ m/} 3.28 \text{ ft}) * 1 \text{ h/} 3600 \text{ s} = 28.2 \text{ m/s}$
 $r = 12 \text{ in} = 30 \text{ cm} = 0.3 \text{ m}$
 $\omega = \frac{v}{r} = \frac{28.2 \text{ m/s}}{0.3 \text{ m}} = 93.9 \text{ rad/s}$
23. $a_{rad} = (6 \text{ rad/s})^2 * 0.5 \text{ m} = 18 \text{ m/s}^2$
 $v = \omega r = 6 \text{ rad/s} * 0.5 \text{ m} = 3 \text{ m/s}$
 $a_{rad} = \frac{v^2}{r} = \frac{(3 \text{ m/s})^2}{0.5 \text{ m}} = 18 \text{ m/s}^2$

25. If the chain doesn't slip, the chain must have the same linear velocity throughout. Therefore,

$$v_8 = v_3 \Rightarrow 8 \omega_8 = 3 \omega_3 \Rightarrow \omega_8 = \frac{3}{8} \omega_3$$

where ω_8 is the angular velocity of the 8 inch wheel,

and ω_3 is the angular velocity of the 3 inch wheel. If the three inch wheel turns at 75 rpm, the 8 inch wheel turns at 3/8 of this, or 28 rpm

27. The radius of the drill bit is 6.35 mm = 0.00635 m. The angular velocity is 130.8 rad/s. The maximum linear speed is then

$$v = \omega r = 130.8 rad/s * 0.00635 m = 0.831 m/s$$
$$a_{rad} = \frac{v^2}{r} = \frac{(0.831 m/s)^2}{0.00635 m} = 109 m/s^2$$
$$29. a_{rad} = \omega^2 r$$

so the ratio of accelerations is :

$$\frac{\omega_{\text{max}}^2}{\omega_{\text{min}}^2} = (640/423)^2 = 2.29$$

(since the radius is the same for the both, it does not effect the ratio).

Tangential speed is $v = \omega r$, so the ratio of linear speeds is the ratio of angular speeds, or 640/423 = 1.51

 $v = \omega r = 67 rad / s * 0.235 m = 15.7 m / s$ $a_{rad} = \omega^2 r = (67 rad / s)^2 * 0.235 m = 1054 m / s^2 = 108 g$